

# Stationary Distributions, Ergodicity, and Detailed Balance

- We want to **simulate samples** from a target distribution  $\pi$ .
- Markov chain theory gives a powerful recipe:
  - ① Construct a Markov chain with transition matrix  $P$ .
  - ② Ensure the chain has **stationary distribution**  $\pi$  (so  $\pi P = \pi$ ).
  - ③ Ensure the chain is **ergodic** (so it *converges* to  $\pi$  from any start).
- Then, after running long enough, the chain's states behave like draws from  $\pi$ .

# Markov chain setup and notation

- Finite state space  $\mathcal{S} = \{1, 2, \dots, m\}$ .
- Transition matrix  $P = (p_{ij})$  where

$$p_{ij} = \mathbb{P}(Y_{n+1} = j \mid Y_n = i), \quad \sum_{j=1}^m p_{ij} = 1, \quad p_{ij} \geq 0.$$

- A probability distribution over states is a **probability vector**

$$q = (q_1, \dots, q_m), \quad q_i \geq 0, \quad \sum_{i=1}^m q_i = 1.$$

- If  $q^{(n)}$  denotes the distribution of  $Y_n$ , then

$$q^{(n+1)} = q^{(n)} P \quad \Rightarrow \quad q^{(n)} = q^{(0)} P^n.$$

## Definition 5.7: Stationary distribution

**Definition 5.7.** Suppose there exists a probability vector  $\pi$  such that

$$\pi P = \pi.$$

Then  $\pi$  is called a **stationary distribution** of the Markov chain.

- $\pi P = \pi$  means  $\pi$  is a **left eigenvector** of  $P$  with eigenvalue 1.
- Intuition: applying one step of the chain *does not change* the distribution.

## Why the name “stationary”? (invariance over time)

If the chain is started at  $\pi$ , i.e.  $q^{(0)} = \pi$ , then

$$q^{(n)} = q^{(0)} P^n = \pi P^n.$$

But since  $\pi P = \pi$ , we get

$$\pi P^n = (\pi P) P^{n-1} = \pi P^{n-1} = \dots = \pi.$$

### Interpretation

Starting the chain in  $\pi$  makes the marginal distribution of  $Y_n$  **constant in time**:

$$\mathbb{P}(Y_n = i) = \pi_i \quad \text{for all } n.$$

## Theorem 5.1: Irreducible $\Rightarrow$ unique stationary distribution

**Theorem 5.1.** If a finite Markov chain is **irreducible**, then a **unique** stationary distribution exists.

- **Irreducible** (recall): every state can be reached from every other state with positive probability in some number of steps.
- What this theorem does *not* say:
  - It does not guarantee that  $q^{(0)}P^n \rightarrow \pi$  as  $n \rightarrow \infty$ .
  - It only guarantees existence and uniqueness of  $\pi$ .

### Takeaway

Uniqueness of  $\pi$  is a **structural** property of the graph of transitions. Convergence needs an extra condition.

## Definition 5.8: Ergodicity (convergence to stationarity)

**Definition 5.8.** A finite Markov chain is called **ergodic** if for all  $i, j \in \mathcal{S}$ ,

$$\lim_{n \rightarrow \infty} \mathbb{P}(Y_n = i \mid Y_0 = j) = \pi_i.$$

- This means: **no matter where you start** ( $Y_0 = j$ ), the distribution at time  $n$  converges to  $\pi$ .

### Equivalent matrix form

For any initial distribution  $q$ ,

$$\lim_{n \rightarrow \infty} qP^n = \pi.$$

## Irreducible is not enough: a 2-state counterexample

Consider the 2-state Markov chain with transition matrix

$$P = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$$

- The chain deterministically alternates:  $1 \rightarrow 2 \rightarrow 1 \rightarrow 2 \rightarrow \dots$
- **Irreducible:** from 1 you can reach 2 in one step; from 2 you can reach 1 in one step.

Stationary distribution exists and is unique

Check that  $\pi = (\frac{1}{2}, \frac{1}{2})$  satisfies  $\pi P = \pi$ :

$$\left(\frac{1}{2}, \frac{1}{2}\right) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \left(\frac{1}{2}, \frac{1}{2}\right).$$

## But it does not converge (periodicity problem)

Start at state 1 with probability 1:

$$q^{(0)} = (1, 0).$$

Then

$$q^{(1)} = q^{(0)}P = (0, 1), \quad q^{(2)} = q^{(1)}P = (1, 0),$$

and in general

$$q^{(2n)} = (1, 0), \quad q^{(2n+1)} = (0, 1).$$

### No convergence

For example,

$$\mathbb{P}(Y_{2n} = 1) = 1 \neq \frac{1}{2} = \pi_1.$$

So  $q^{(0)}P^n$  does **not** approach  $\pi$ .

- The chain keeps **oscillating** rather than mixing.

# Aperiodicity: what went wrong?

The issue is **periodicity**. In the 2-state alternating chain:

- You return to state 1 only at even times:  $n = 2, 4, 6, \dots$
- You return to state 2 only at even times as well.

## Period (informal)

The period of a state is the gcd of all return times with positive probability. Here both states have period 2:

$$d_1 = d_2 = 2 > 1.$$

- A chain is **aperiodic** if all states have period 1.
- Aperiodicity prevents this kind of deterministic “cycling”.

## Theorem 5.2: Characterisation of ergodicity

**Theorem 5.2.** A finite Markov chain is **ergodic** if and only if it is

- **irreducible**, and
- **aperiodic**.

### Meaning

If the chain is irreducible + aperiodic, then for any start  $q$ ,

$$qP^n \longrightarrow \pi,$$

where  $\pi$  is the unique stationary distribution.

- This is the key convergence guarantee used in MCMC.

# MCMC interpretation: why ergodicity matters

- In MCMC we want to sample from a **target distribution**  $\pi$ .
- We build a Markov chain whose stationary distribution is  $\pi$ .
- If the chain is ergodic, then:
  - regardless of initialisation,  $Y_n$  eventually behaves like a draw from  $\pi$ ;
  - empirical averages along the chain approximate expectations under  $\pi$ .

## Practical wording

It may take a while to “reach stationarity” (burn-in / mixing), but in principle an ergodic chain will get there.

# Checklist for convergence to the stationary distribution

To ensure a finite Markov chain converges to its stationary distribution, check:

- 1 **Irreducible** (can reach everywhere).
- 2 **Aperiodic** (does not get trapped in cycles).

If you also want to sample from a *prescribed* target  $\pi$ , you additionally need:

- 3  **$\pi$  is stationary:**  $\pi P = \pi$ .

## Two separate design goals

(1)–(2) guarantee convergence *to something*; (3) ensures the “something” is the distribution you want.

## Example 5.2: King Markov and prescribed stationarity

Recall Example 5.1 (the King and the ring of islands):

- States are islands  $i = 1, \dots, 10$ .
- Target long-run behaviour: spend time proportional to island size:

$$\mathbb{P}(Y = i) \propto i.$$

- The King's proposal-and-accept rule was designed so that:
  - the chain is **aperiodic** (not stuck in a regular alternating cycle);
  - the chain is **irreducible** (can reach all islands);
  - the resulting stationary distribution matches  $\pi(i) \propto i$ .

Designing irreducible + aperiodic chains is often straightforward. Designing a chain with a **prescribed stationary distribution** is the subtle part.

# How to enforce a desired stationary distribution?

Suppose we want a chain with stationary distribution  $\pi$ .

- Directly solving  $\pi P = \pi$  can be awkward, because  $P$  must also:
  - have nonnegative entries,
  - have rows summing to 1,
  - satisfy irreducible + aperiodic structure.
- A very useful sufficient condition is **detailed balance**.

## Key idea

Instead of enforcing the global condition  $\pi P = \pi$ , we enforce a *pairwise symmetry of flow* between every pair of states.

## Definition 5.9: Detailed balance

**Definition 5.9.** A Markov chain with transition matrix  $P$  satisfies the **detailed balance equation** with respect to  $\pi$  if for all states  $i, j$ ,

$$\pi_i p_{ij} = \pi_j p_{ji}.$$

- $\pi_i p_{ij}$  is the probability mass *flowing* from  $i$  to  $j$  in one step if the chain is distributed as  $\pi$ .
- Detailed balance says: for each pair  $(i, j)$  the flow  $i \rightarrow j$  equals the flow  $j \rightarrow i$ .

### Interpretation

No net flow anywhere  $\Rightarrow$  distribution stays unchanged  $\Rightarrow$  stationarity.

## Theorem 5.3: Detailed balance $\Rightarrow$ stationarity

**Theorem 5.3 (Detailed Balance).** Let  $P$  satisfy detailed balance with respect to  $\pi$ . Then

$$\pi P = \pi,$$

so  $\pi$  is stationary.

- This theorem provides a convenient way to **construct** Markov chains with a known stationary distribution.
- Many MCMC algorithms (e.g. Metropolis–Hastings) are designed by enforcing detailed balance.

## Proof of Theorem 5.3 (line by line)

We prove that the  $j$ th entry of  $\pi P$  equals  $\pi_j$ .

The  $j$ th entry is:

$$(\pi P)_j = \sum_i \pi_i p_{ij}.$$

Using detailed balance  $\pi_i p_{ij} = \pi_j p_{ji}$ :

$$\sum_i \pi_i p_{ij} = \sum_i \pi_j p_{ji} = \pi_j \sum_i p_{ji}.$$

Now use that probabilities out of state  $j$  sum to 1:

$$\sum_i p_{ji} = 1 \quad \Rightarrow \quad (\pi P)_j = \pi_j.$$

### Conclusion

Since this holds for every  $j$ , we have  $\pi P = \pi$ .

# Putting it together: the MCMC design recipe

To sample from a target distribution  $\pi$  using a Markov chain:

- 1 Choose a state space  $\mathcal{S}$  and a transition mechanism.
- 2 Ensure **irreducibility** (connect the space).
- 3 Ensure **aperiodicity** (avoid deterministic cycles).
- 4 Ensure **stationarity** of  $\pi$ :
  - often via **detailed balance**:  $\pi_i p_{ij} = \pi_j p_{ji}$ .

## Guarantee

Then the chain is ergodic and

$$qP^n \rightarrow \pi \quad \text{for any initial } q,$$

so long-run samples behave like draws from  $\pi$ .

## A quick comment: why do this for discrete $\pi$ ?

So far, everything was for **finite** state Markov chains.

- If  $\pi$  is a discrete distribution on a finite set, we can already sample from it directly (e.g. inverse transform / alias method).
- So using a Markov chain can feel like **overkill** in the finite-discrete case.

### Why we still study it

The same concepts generalise naturally to:

- countably infinite state spaces,
- continuous state spaces (e.g.  $\mathbb{R}^d$ ),
- complicated posteriors in Bayesian inference.

That is where MCMC becomes essential.

# Transition to general state spaces (preview)

- In continuous or high-dimensional problems we often cannot:
  - write down the normalising constant of  $\pi$ ,
  - sample from  $\pi$  directly.
- We therefore construct a Markov chain whose stationary distribution is  $\pi$  and rely on ergodic convergence.

## Next

We will extend these ideas from finite transition matrices to **Markov kernels** and algorithms like **Metropolis–Hastings**.