

4.5 Approximate Bayesian Computation (ABC)

Likelihood-free inference via rejection from the prior

Where we are so far: likelihood-based Bayes

So far, our Bayesian workflows assumed the likelihood is **easy to work with**:

- We can **evaluate** $\pi(y \mid \theta)$ at many values of θ .
- We can evaluate it **cheaply**, so MCMC / optimisation are feasible.

But sometimes:

- the likelihood is **not available in closed form**, or
- it is **too expensive** to evaluate.

Terminology: methods that do inference without evaluating $\pi(y \mid \theta)$ are called **likelihood-free inference**.

Motivating example: complex weather models (Example 4.6)

Weather forecasting models can be extremely complex:

- huge numbers of parameters,
- complicated dynamics,
- potentially no exact tractable likelihood.

Even if a likelihood can be written down in principle, it may be impractical:

- evaluating $\pi(y \mid \theta)$ may be too slow,
- and re-running a full MCMC pipeline every time new data arrive is costly.

Key idea for ABC: often we *can* still **simulate data** from the model for a given θ , even if we cannot compute the likelihood.

ABC in one sentence

Approximate Bayesian Computation (ABC) is a likelihood-free approach that replaces
“evaluate likelihood of observed data” \longrightarrow “simulate fake data and compare to observed data”.

ABC typically needs:

- a prior $\pi(\theta)$,
- a simulator $y^* \sim \pi(\cdot \mid \theta)$ (data-generating process),
- a notion of **closeness** (distance and tolerance ε).

Today: two basic ABC variants:

- 1 ABC with rejection (compare full data),
- 2 Summary ABC with rejection (compare summary statistics).

ABC with rejection: algorithm (Definition 4.2)

Goal: approximate the posterior $\pi(\theta \mid y)$ without computing $\pi(y \mid \theta)$.

ABC rejection algorithm:

- 1 Sample $\theta^* \sim \pi(\theta)$ (from the prior).
- 2 Simulate $y^* \sim \pi(\cdot \mid \theta^*)$ (generate synthetic data).
- 3 Accept θ^* if $\|y - y^*\| < \varepsilon$ for some $\varepsilon > 0$, otherwise reject.
- 4 Repeat steps 1–3 until you have enough accepted samples.

Interpretation:

- We keep parameter values that can generate data *similar* to what we observed.
- Similarity is controlled by a **tolerance** ε .

What distribution are we sampling from? (Definition 4.3)

Define the acceptance region

$$A_\varepsilon(y^\star) = \{y^\star : \|y^\star - y\| < \varepsilon\}.$$

Then the ABC-rejection samples target the **approximate posterior**

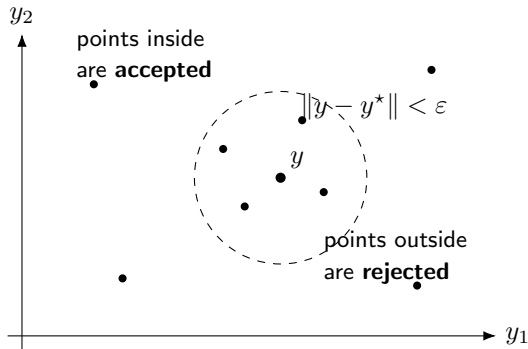
$$\pi_\varepsilon(\theta | y) \propto \int \pi(y^\star | \theta) \pi(\theta) \mathbf{1}_{A_\varepsilon}(y^\star) dy^\star.$$

Plain English:

- For each θ , we look at the probability that simulated data y^\star lands within distance ε of the observed data y .
- Multiply by the prior, and renormalise.

A picture: acceptance as a “ball” around the data

Think of y and y^* as vectors in \mathbb{R}^n .



Key message: as dimension n grows, it becomes much harder for random y^* to fall inside a small ε -ball.

Example 4.7: model setup

We observe data

$$y_1, \dots, y_{10} \sim \text{Beta}(3, \beta).$$

We place a prior on the unknown parameter β :

$$\beta \sim \text{Unif}[0, 5].$$

ABC idea here:

- propose β^* from the prior,
- simulate synthetic data y_1^*, \dots, y_{10}^* from $\text{Beta}(3, \beta^*)$,
- accept if simulated data is “close” to observed data.

Example 4.7: distance and acceptance rule

Choose a distance (here: squared error across all data points):

$$D = \sum_{i=1}^{10} (y_i - y_i^*)^2.$$

Acceptance rule:

accept β^* if $D < \varepsilon$,

with (in the example) $\varepsilon = 0.75$.

Notes:

- This D is just one choice; many distances are possible.
- ε controls the approximation–computation trade-off.

Example 4.7: R code (ABC rejection)

```
# Set Up Example
set.seed(1234)
n <- 10
y <- rbeta(n, 3, 2)

# Set Up ABC
n.iter <- 50000
b.store <- numeric(n.iter)
epsilon <- 0.75

# Run ABC
for(i in 1:n.iter){

  # Propose new beta
  b <- runif(1, 0, 5)

  # Simulate data
  y.sim <- rbeta(n, 3, 1)
```

Example 4.7: reading the output

In the provided run (with $\varepsilon = 0.75$):

- many proposals are rejected (acceptance rate is low),
- the histogram of accepted β^* values approximates the posterior shape,
- the red vertical line at $\beta = 2$ is the **true** value used to generate y (only for this toy demo).

You can summarise the approximate posterior via:

- posterior mean (sample mean of accepted draws),
- credible intervals (quantiles of accepted draws).

But: all results can change substantially with ε .

The big practical question: how do we choose ε ?

Choosing ε is **application-specific** and often difficult.

Two competing effects:

- **Small** $\varepsilon \Rightarrow$ better approximation to $\pi(\theta \mid y)$, but very low acceptance (slow / few samples).
- **Large** $\varepsilon \Rightarrow$ high acceptance, but poor approximation (can collapse back to the prior).

In practice, common diagnostics are:

- acceptance rate (how many draws are not NA),
- comparing histograms of the approximate posterior vs the prior,
- stability of posterior summaries across nearby ε values.

Example 4.8: very small tolerance ($\varepsilon = 0.12$)

With $\varepsilon = 0.12$, almost all proposals are rejected.

```
epsilon <- 0.12

# ... same loop ...
sum(is.na(b.store)) # almost all rejected
hist(b.store, freq = FALSE, xlab = expression(beta), main = "")
abline(v = 2, col = "red")

mean(b.store, na.rm = TRUE)
quantile(b.store, c(0.025, 0.975), na.rm = TRUE)
```

Interpretation:

- The few accepted samples might be close to the truth,
- but with tiny sample size, the histogram / quantiles are very noisy.

Example 4.9: very large tolerance ($\varepsilon = 2$)

With $\varepsilon = 2$, almost all proposals are accepted.

```
epsilon <- 2

# ... same loop ...
sum(is.na(b.store)) # very few rejected
hist(b.store, freq = FALSE, xlab = expression(beta), main = "")
abline(v = 2, col = "red")
```

Interpretation:

- If almost everything is accepted, the accepted β^* values look like the prior,
- meaning we have learned very little from the data.

Limiting behaviour (Proposition 4.2)

ABC with rejection interpolates between the prior and the true posterior:

$$\lim_{\varepsilon \rightarrow \infty} \pi_{\varepsilon}(\theta \mid y) \stackrel{D}{=} \pi(\theta), \quad \lim_{\varepsilon \rightarrow 0} \pi_{\varepsilon}(\theta \mid y) \stackrel{D}{=} \pi(\theta \mid y).$$

Why this makes sense:

- If ε is huge, almost every y^* counts as “close” \Rightarrow we accept almost every θ^* from the prior.
- If ε is tiny, only θ^* that can generate (almost) the exact observed data are accepted \Rightarrow we recover the true posterior in the limit.

A practical trade-off

The proposition suggests: **smaller ε is better.**

But in real computation:

- Very small ε can mean **near-zero acceptance**, leading to:
 - huge run time, or
 - so few accepted samples that Monte Carlo noise dominates.
- Larger ε increases acceptance but can blur the posterior and bias inference.

Rule of thumb: monitor both

acceptance rate and how different the posterior looks from the prior.

Why ABC with full data struggles: curse of dimensionality

ABC rejection compares full datasets via $\|y - y^*\|$.

As the number of data points n increases:

- y and y^* live in higher-dimensional space,
- the probability that a random y^* lands close to y becomes tiny,
- to accept anything we often must increase ε ,
- which **degrades** the approximation.

Example 4.10 (conceptual): for the Beta example with $n = 200$, we may need $\varepsilon > 15$ just to get non-zero acceptance *when comparing full data*.

Idea: compare summary statistics instead

Instead of comparing the entire datasets, compare a **summary**:

$$S(y) \in \mathbb{R}^k,$$

where k is small (e.g. $k = 1$ for the mean).

Benefit:

- lower-dimensional matching is easier,
- acceptance rates improve dramatically for large n .

Cost:

- we introduce an *additional approximation* because $S(y)$ throws away information.

Summary ABC with rejection: algorithm (Definition 4.4)

Summary ABC rejection algorithm:

- 1 Sample $\theta^* \sim \pi(\theta)$.
- 2 Simulate $y^* \sim \pi(\cdot \mid \theta^*)$.
- 3 Accept θ^* if

$$\|S(y) - S(y^*)\| < \varepsilon,$$

otherwise reject.

- 4 Repeat.

Key difference from basic ABC: we match in the space of summary statistics.

Approximate posterior for Summary ABC (Proposition 4.3)

Define acceptance set in summary space:

$$A_\varepsilon(y^\star) = \{y^\star : \|S(y^\star) - S(y)\| < \varepsilon\}.$$

Then the Summary-ABC approximate posterior can be written as

$$\pi_\varepsilon(\theta \mid S(y)) \propto \int \pi(y^\star \mid \theta) \pi(\theta) \mathbf{1}_{A_\varepsilon}(y^\star) dy^\star.$$

Same structure as before, but with acceptance defined using $S(\cdot)$ rather than the full data.

Sufficient statistics: when Summary ABC can be exact

Using summaries generally increases approximation, *unless* the summary contains all information about θ .

Definition 4.5 (Sufficient statistic): A statistic S is sufficient for θ if the conditional distribution

$$\pi(y \mid S(y))$$

does **not** depend on θ .

Intuition:

- Once you know $S(y)$, the remaining details of y are irrelevant for learning θ .

Consequence (Proposition 4.4)

If S is sufficient, Summary ABC can recover the true posterior in the small-tolerance limit:

$$\lim_{\varepsilon \rightarrow 0} \pi_{\varepsilon}(\theta \mid S(y)) \stackrel{D}{=} \pi(\theta \mid y).$$

Reality check:

- Sufficient statistics typically exist only for “nice” families (e.g. Beta, Gamma, Poisson with standard sampling models).
- In those cases we often can do exact Bayes anyway, so ABC is not necessary.

Example 4.11: Beta example with mean as summary

Repeat the Beta example but now with:

- $n = 200$ observations,
- summary statistic $S(y) = \bar{y}$ (sample mean),
- tolerance $\varepsilon = 0.001$.

Important: the mean is *not* sufficient for β in $\text{Beta}(3, \beta)$, so there is an additional approximation even as $\varepsilon \rightarrow 0$.

Example 4.11: R code (Summary ABC with mean)

```
set.seed(1234)
n <- 200
y <- rbeta(n, 3, 2)

n.iter <- 50000
b.store <- numeric(n.iter)
epsilon <- 0.001

for(i in 1:n.iter){

  b <- runif(1, 0, 5)
  y.star <- rbeta(n, 3, b)

  # summary distance in 1D (mean)
  d <- (mean(y) - mean(y.star))^2

  if(d < epsilon){
```


What improved, and what did we pay?

With summary statistics:

- **Improvement:** matching in low dimension is easier, so we can use a much smaller ε and still accept a reasonable number of draws.
- **Cost:** we are no longer targeting $\pi(\theta \mid y)$ but rather something closer to

$$\pi(\theta \mid S(y)),$$

which can lose information when S is not sufficient.

Takeaway:

- Summary ABC reduces the curse of dimensionality,
- but forces you to think carefully about which summaries preserve the information you care about.

Key takeaways (4.5)

- ABC is **likelihood-free**: it replaces likelihood evaluation by **simulation + comparison**.
- ABC rejection:
 - propose θ^* from the prior,
 - simulate y^* ,
 - accept if $\|y - y^*\| < \varepsilon$.
- Tolerance ε controls:

$\varepsilon \downarrow \Rightarrow$ better approximation but lower acceptance.

- Limits:

$\varepsilon \rightarrow \infty \Rightarrow$ recover prior, $\varepsilon \rightarrow 0 \Rightarrow$ recover posterior (in ideal limit).

- Curse of dimensionality motivates **Summary ABC**: match $\|S(y) - S(y^*)\|$ instead.
- If S is **sufficient**, Summary ABC can be exact as $\varepsilon \rightarrow 0$; otherwise it introduces extra approximation.

Practical diagnostics for ABC

When running ABC in practice, always check:

- **Acceptance rate:** too low \Rightarrow too few samples; too high \Rightarrow likely close to the prior.
- **Sensitivity to ε :** do posterior summaries change a lot when you adjust ε slightly?
- **Prior vs posterior:** does the approximate posterior look meaningfully different from the prior?
- **Choice of distance and summaries:** are you matching features of the data that matter for θ ?

Next steps (later chapters): more efficient ABC variants (e.g. sequential methods) and links to MCMC ideas.